

Courant Algebroids

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Outline

- Why?
- What?
- How?
- Where?

Algebroids generalize the standard differential geometry and the notion of linear algebras.

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Certain Courant algebroid provides a geometrical playground for the physical theory of supergravity.

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Notation I

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- Module of generalized (p, q) —tensors on M :



Note: Whenever our vector bundle turns out to be the tangent bundle, we shall simplify the notation such as in the following:

$$\mathcal{T}_q^P(M; TM) =: \mathcal{T}_q^P(M)$$

Leibniz Algebra

Leibniz algebra L is a vector space with a bilinear mapping:

$$[\cdot, \cdot] : L \times L \rightarrow L$$

such that the Leibniz identity holds, that is:

$$[a, [b, c]] = [[a, b], c] + [b, [a, c]]$$

for all $a, b, c \in L$.

Leibniz Algebroid

Leibniz algebroid is a vector bundle (E, π, M) along with a vector bundle homomorphism $\rho : E \rightarrow TM$ and a bilinear mapping:

$$[\cdot, \cdot]_E : \Gamma(E) \times \Gamma(E) \rightarrow \Gamma(E)$$

such that the Leibniz identity and Leibniz rule in the second input hold, that is:

$$[e, [e', e'']_E]_E = [[e, e']_E, e'']_E + [e', [e, e'']_E]_E,$$

$$[e, fe']_E = f[e, e']_E + (\rho(e) \cdot f)e'.$$

The map ρ is called the anchor of Leibniz algebroid.

Generalized Lie Derivative

Generalized Lie derivative \mathcal{L}^E along the section e of E is linear operator on the graded algebra of generalized tensor fields on M defined in the following way:

$$\mathcal{L}_e^E f = \rho(e) \cdot f, \quad \forall f \in C^\infty(M),$$

$$\mathcal{L}_e^E e' = [e, e']_E, \quad \forall e' \in \Gamma(E),$$

$$\langle \mathcal{L}_e^E \alpha, e' \rangle = \rho(e) \cdot \langle \alpha, e' \rangle - \langle \alpha, [e, e']_E \rangle, \quad \forall \alpha \in \Gamma(E^*), e' \in \Gamma(E),$$

$$\begin{aligned} [\mathcal{L}_e^E \tau](e_1, \dots, e_q; \alpha_1, \dots, \alpha_p) &= \rho(e) \tau(e_1, \dots, e_q; \alpha_1, \dots, \alpha_p) \\ &\quad - \tau(\mathcal{L}_e^E e_1, \dots, e_q; \alpha_1, \dots, \alpha_p) - \dots - \tau(e_1, \dots, e_q; \alpha_1, \dots, \mathcal{L}_e^E \alpha_p) \\ \forall e_1, \dots, e_q \in \Gamma(E), \alpha_1, \dots, \alpha_p \in \Gamma(E^*), \tau \in \mathcal{T}_q^p(M; E) \end{aligned}$$

Examples:

- $(TM \xrightarrow{\pi} M, id_{TM}, [\cdot, \cdot])$
- $(L \xrightarrow{\pi} m, 0, [\cdot, \cdot])$
- $(TM \oplus \Lambda^p T^*M \xrightarrow{\pi} M, pr_1, [\cdot, \cdot]_D)$, with the Dorfman bracket $[\cdot, \cdot]_D$ defined as:

$$[X + \xi, Y + \eta]_D := [X, Y] + \mathcal{L}_X \eta - i_Y d\xi$$

$$\forall X, Y \in \mathfrak{X}(M) \text{ and } \xi, \eta \in \Omega^p(M)$$

Grupoid

Grupoid consists of two sets G and M with two maps $\alpha, \beta : G \rightarrow M$ called source and target, the so-called object inclusion map $1_M : M \rightarrow G$ and a partial multiplication function in G such that the following holds:

- $\alpha(hg) = \alpha(g), \beta(hg) = \beta(h),$
- $j(hg) = (jh)g,$
- $\alpha(1_x) = \beta(1_x) = x,$
- $g1_{\alpha(g)} = g, 1_{\beta(g)}g = g$

$\forall j, h, g \in G$ and $x \in M$ whenever the partial multiplication between such elements is defined. Each element $g \in G$ also has its two-sided inverse $g^{-1} \in G$.

Note: The definition of grupoid can be smoothly rephrased using category theoretical language by simply stating that a grupoid is a category where each morphism is isomorphism.

Lie Grupoid

Lie grupoid (G, M) involves besides the standard grupoid data also a smooth manifold structure on both G and M .

Lie Algebra

Lie algebra is a vector space \mathcal{G} equipped with a bilinear mapping:

$$[\cdot, \cdot] : \mathcal{G} \times \mathcal{G} \rightarrow \mathcal{G}$$

such that the Jacobi identity holds and the mapping alternates, that is:

$$[x, [y, z]] + [y, [z, x]] + [z, [x, y]] = 0,$$

$$[x, x] = 0,$$

$$\forall x, y, z \in \mathcal{G}.$$

Lie Algebroid

Lie algebroid is a Leibniz algebroid $(L \xrightarrow{\pi} M, l, [\cdot, \cdot]_L)$, for which the Leibniz bracket alternates.

Note: Another way to define Lie algebroid is to say that it is a vector bundle over the set of units of a Lie grupoid.

Generalized Differential

In the Lie algebroid settings, there is an operator $d_L : \Omega^\bullet(M; L) \rightarrow \Omega^{\bullet+1}(M; L)$ on the generalized exterior algebra defined as follows:

$$(d_L \omega)(e_0, e_1, \dots, e_p) := \sum_{i=0}^p (-1)^i l(e_i) \omega(e_0, \dots, \hat{e}_i, \dots, e_p) + \sum_{i < j} (-1)^{i+j} \omega([e_i, e_j]_L, e_0, \dots, \hat{e}_i, \dots, \hat{e}_j, \dots, e_p)$$

$\forall \omega \in \Omega^p(M; L)$ and $e_0, e_1, \dots, e_p \in \Gamma(L)$.

Note: The generalized differential encodes the entire Lie algebroid information.

Examples:

- $(TM \xrightarrow{\pi} M, id_{TM}, [\cdot, \cdot]),$
- $(\mathcal{G} \xrightarrow{\pi} m, 0, [\cdot, \cdot]),$
- $(T^*M \xrightarrow{\pi'} M, \Pi, [\cdot, \cdot]_{\Pi})$ with:

$$\Pi(\alpha) \equiv \Pi(\alpha, \cdot) \text{ and } [\alpha, \beta]_{\Pi} = \mathcal{L}_{\Pi(\alpha, \cdot)}\beta - i_{\Pi(\beta, \cdot)}d\alpha$$

where $\Pi \in \mathfrak{X}^2(M).$

Fiber-wise Metric

Fiber-wise metric on a vector bundle is a symmetric bilinear non-degenerate form $\langle \cdot, \cdot \rangle_E : \Gamma(E) \times \Gamma(E) \rightarrow C^\infty(M)$.

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Courant Algebroid

Courant algebroid is a pair of Leibniz algebroid and a fiber-wise metric $(E \xrightarrow{\pi} M, \rho, [\cdot, \cdot]_E, \langle \cdot, \cdot \rangle_E)$, such that:

$$\rho(e) \cdot \langle e', e'' \rangle_E = \langle [e, e']_E, e'' \rangle_E + \langle e', [e, e'']_E \rangle_E,$$

$$\langle [e, e']_E, e' \rangle_E = \frac{1}{2} \rho(e') \cdot \langle e, e \rangle_E,$$

$$\forall e, e', e'' \in \Gamma(E).$$

Note: Equivalently, we have $\mathcal{L}_e^E g_E = 0$ and $[e, e]_E = \frac{1}{2} \mathcal{D} \langle e, e \rangle_E$ for each $e \in \Gamma(E)$ where g_E is the tensor corresponding to the fiber-wise metric and $\mathcal{D} = g_E^{-1} \circ \rho^T \circ d : C^\infty(M) \rightarrow \Gamma(E)$.

Examples:

- $(\mathcal{G} \xrightarrow{\pi} m, [\cdot, \cdot], \langle \cdot, \cdot \rangle)$, for \mathcal{G} a quadratic Lie algebra
- $(TM \oplus T^*M \xrightarrow{\pi} M, pr_1, [\cdot, \cdot]_D, \langle \cdot, \cdot \rangle)$, for $[\cdot, \cdot]_D$ a Dorfman bracket and $\langle \cdot, \cdot \rangle$ a canonical pairing,
- $(TM \oplus T^*M \xrightarrow{\pi} M, pr_1, [\cdot, \cdot]_D^H, \langle \cdot, \cdot \rangle)$, for $[\cdot, \cdot]_D^H$ an H -twisted Dorfman bracket defined as $[X + \xi, Y + \eta]_D^H := [X + \xi, Y + \eta]_D - H(X, Y, \cdot)$ where $H \in \Omega^3(M)$

Courant Algebroid Connection

Courant algebroid connection is a map $\nabla : \Gamma(E) \times \Gamma(E) \rightarrow \Gamma(E)$ for which $\nabla(fe, e') = f\nabla(e, e')$ and $\nabla(e, fe') = f\nabla(e, e') + (\rho(e) \cdot f)e'$ for each $e, e' \in \Gamma(E)$ and ∇ is compatible with the Courant algebroid metric.

Example:

For Courant algebroid $(TM \oplus T^*M \xrightarrow{\pi} M, \rho, [\cdot, \cdot]_D, \langle \cdot, \cdot \rangle_E)$ we may define a Courant algebroid connection ∇ in the following way:

$$\langle \nabla_a b, c \rangle_E := \langle [a, b]_D - [a, b]_E, c \rangle_E$$

for $a, b, c \in \Gamma(E)$ and $[\cdot, \cdot]_E : \Gamma(E) \times \Gamma(E) \rightarrow \Gamma(E)$ an arbitrary skew-symmetric bracket with Leibniz rule.

(Here E is a shorthand notation for $TM \oplus T^*M$.)

Conclusion

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- This formalism also allows for the generalization of linear algebras.
- There is a theorem of Roytenberg and Ševera giving us a one-to-one correspondence between Courant algebroids and Poisson manifolds with a nilpotent vector field on them.

“My name’s Jeff.” - Jeff

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